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	Filing Date		2004-03-26
	First Named Inventor	Jeffrey J. Berkley	
	Art Unit	2629	
	Examiner Name	Alexander S. Beck	
	Attorney Docket Number	660119.401	

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	1	20080150891	A1	2008-06-26	Berkley et al.	

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1	CyberGlove II, URL= http://www.cyberglovesystems.com/products/cyberglove-ii/overview , download date August 9, 2010, 1 page.	<input type="checkbox"/>
2	HASHIMOTO et al., "Intuitive and Effective 3-D Modeler in CAVE," IEIC Technical Report 99(184):9-16, 1999 (English Abstract only).	<input type="checkbox"/>
3	HASHIMOTO et al., "Development of Haptic Device on a Human-Scale Virtual Reality Environment," Human Interface 2000 Tsukuba, 2000, pp. 423-426.	<input type="checkbox"/>
4	HATANO et al., "Six Degree of Freedom Master Using Eight Tensed Strings," Proceedings of the Eighth International Symposium on Measurement and Control in Robotics, June 8-12, 1998, Prague, Czechoslovakia, pp. 251-255.	<input type="checkbox"/>
5	IISHI et al., "Force Sensations in Pick-and-Place Tasks," Dynamic Systems and Control - ASME 1994, DSC-Vol. 55-1, pp. 339-344.	<input type="checkbox"/>
6	OTTENSMEYER et al., "Input and Output for Surgical Simulation: Devices to Measure Tissue Properties in vivo and a Haptic Interface for Laparoscopy Simulators," Medicine Meets Virtual Reality 2000, pp. 236-242.	<input type="checkbox"/>
7	BEN-UR, "Development of a Force-Feedback Laparoscopic Surgery Simulator," Master's Thesis, Massachusetts Institute of Technology, September 1999, 114 pages.	<input type="checkbox"/>
8	International Search Report, mailed February 3, 2005, for PCT/US2004/009295, 1 page.	<input type="checkbox"/>
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